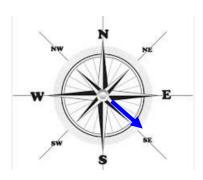
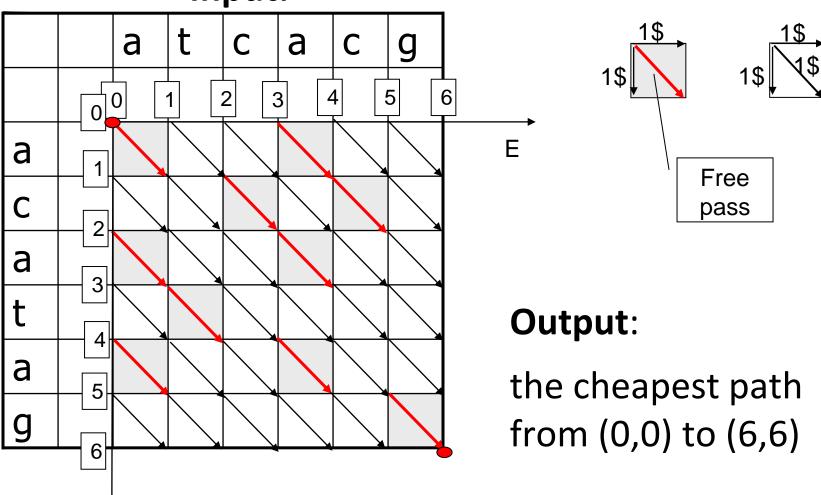
Dynamic Programming

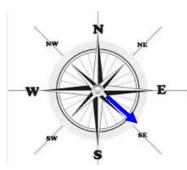
Lecture 07.01 by Marina Barsky



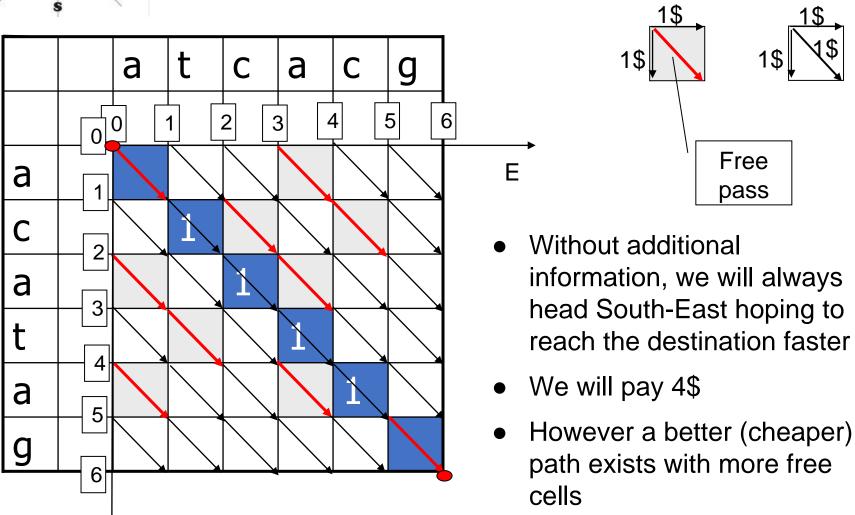
Problem: the cheapest path in a special grid

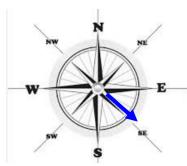
Input:



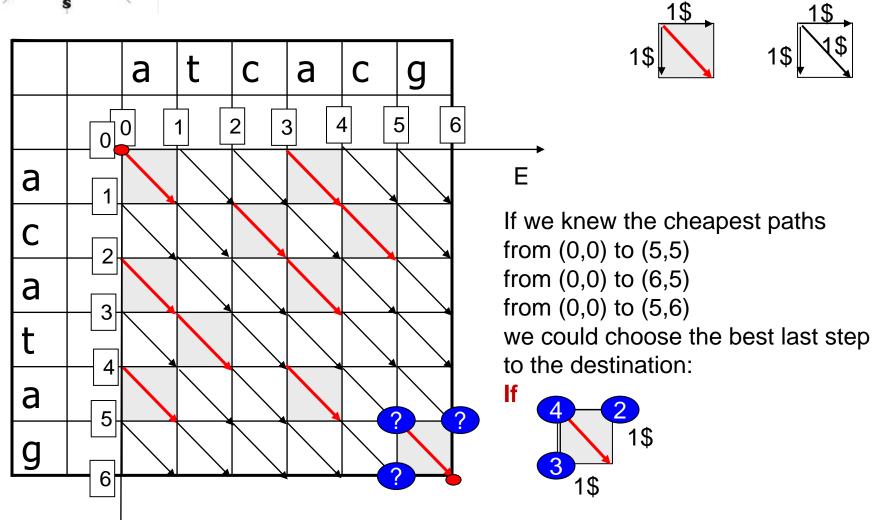


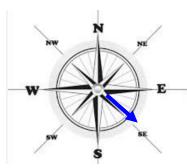
Without the map



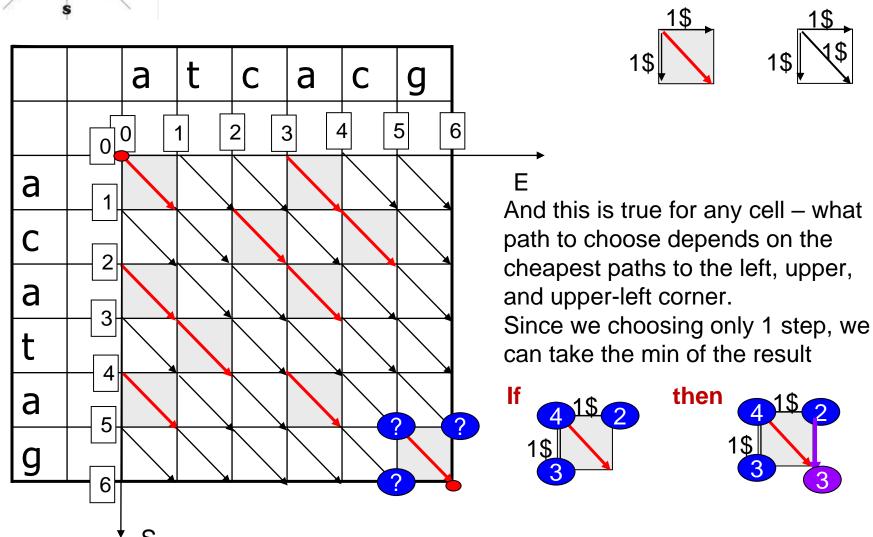


Sub-problems approach

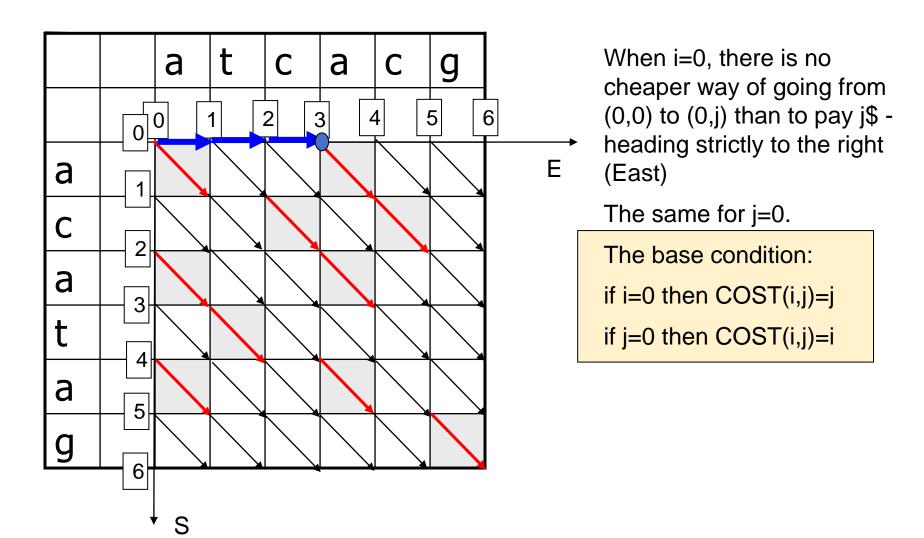




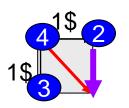
Sub-problems approach



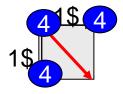
Recurrence relation – base condition

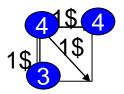


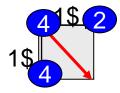
Recurrence relation (for i>0 and j>0)



$$COST(i,j) = min \begin{cases} COST(i-1,j)+1 \\ COST(i,j-1)+1 \\ COST(i-1,j-1)+DIAGONAL(i,j) \end{cases}$$

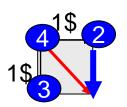






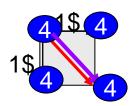
For each case, what is the best choice?

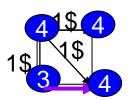
Recurrence relation (for i>0 and j>0)

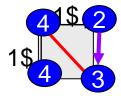


$$COST(i,j)= min \left\{ \begin{array}{l} COST(i-1,j)+1 \\ COST(i,j-1)+1 \\ COST(i-1,j-1)+DIAGONAL(i,j) \end{array} \right.$$

For each case, what is the best choice?







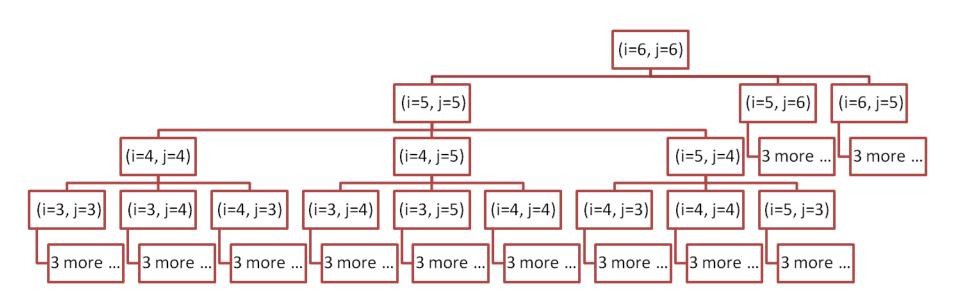
Recursive algorithm

```
COST(i,j)= min \begin{cases} COST(i-1,j)+1 \\ COST(i,j-1)+1 \\ COST(i-1,j-1)+DIAGONAL(i,j) \end{cases}
```

```
algorithm cheapestPath ( array diagonalCost, N, M)
    return cost ( N, M, diagonalCost)

algorithm cost ( i, j, diagonalCost)
    if i=0 then
        return j
    if j=0 then
        return i
    return min (cost ( i-1, j ) +1, cost ( i, j-1)+1, cost ( i-1, j-1)+diagonalCost [i] [j] )
```

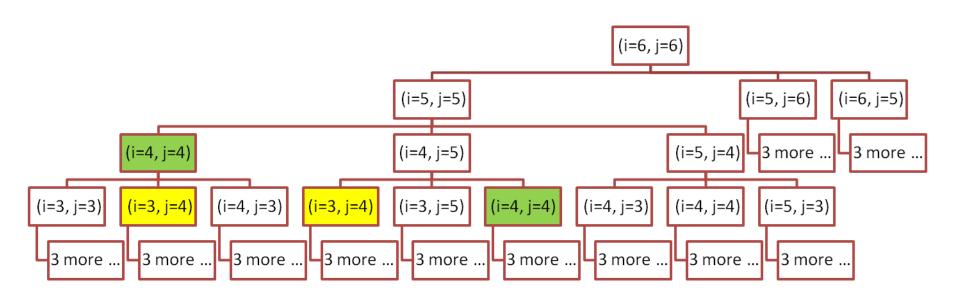
The recursion tree: $O(3^N)$



 $O(3^{N})$?

But there are only N*M different combinations (*i,j*)!

Recursive algorithm: O(3^N)



The algorithm is exponential in N because we call the recursive function multiple times with the same parameters!

Idea 1: store intermediate results

- Store the results of the cost(i,j) in a 2D table so they do not need to be recomputed when needed again
- There are at most N² different combinations of (*i,j*)
- For each combination of (i,j) we compute the cost(i,j) only once
- When we need cost(i,j) again, we first check if it is already computed
- This gives a total running time O(N²)
- The method of storing the results of recursive calls in a lookup table is called recursion with memoization

Idea 2: The bottom-up computation

- In this particular problem we would need to compute the cost for all combinations of (*i*, *j*)
- Hence, instead of starting from cost(N,M) fill in the best values for each cell of N*M table starting from the lowest values

The bottom-up computation

- Create a table of size(NxM) to store results of cost(i, j) for each $0 \le i \le N$ and $0 \le j \le M$
- First, fill-in the basic values of recursion for *i*=0 and for *j*=0
- Apply recursive formula for computing the value of each cell from the lowest numbers of i and j to the highest (by rows or by columns)
- At the end, we will have the cost of the best path in the cell (N, M)

The recurrence relation: stays the same

The base condition:

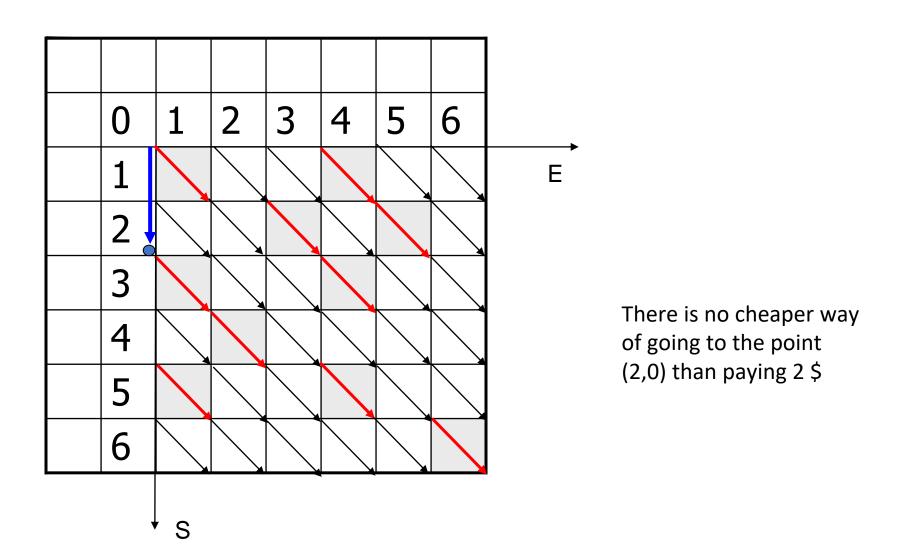
```
if i=0 then COST(i,j)=j
if j=0 then COST(i,j)=i
```

The main relation (for i>0 and j>0)

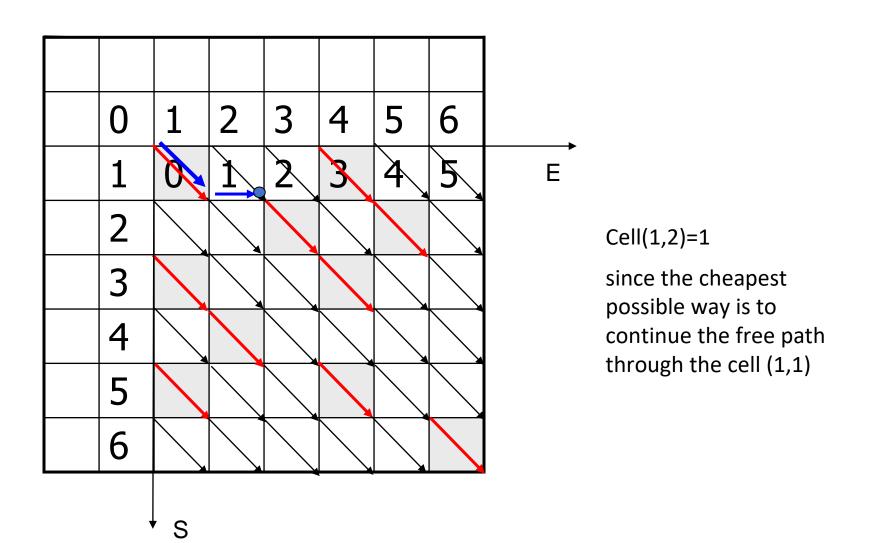
$$\begin{array}{c} & \text{COST(i-1,j)+1} \\ & \text{COST(i,j-1)+1} \\ & \text{COST(i-1,j-1)+DIAGONAL(i,j)} \end{array}$$

We change: the order of computation

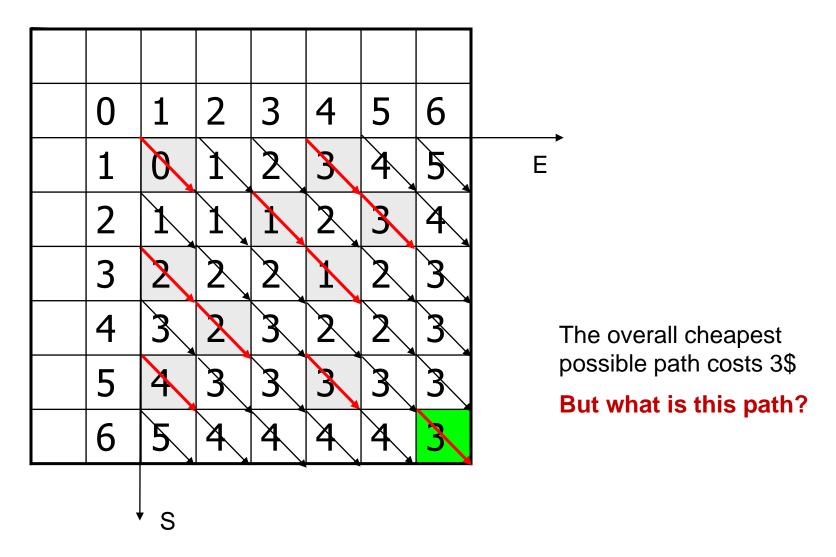
Fill values for i=0 and for j=0 (the base case)



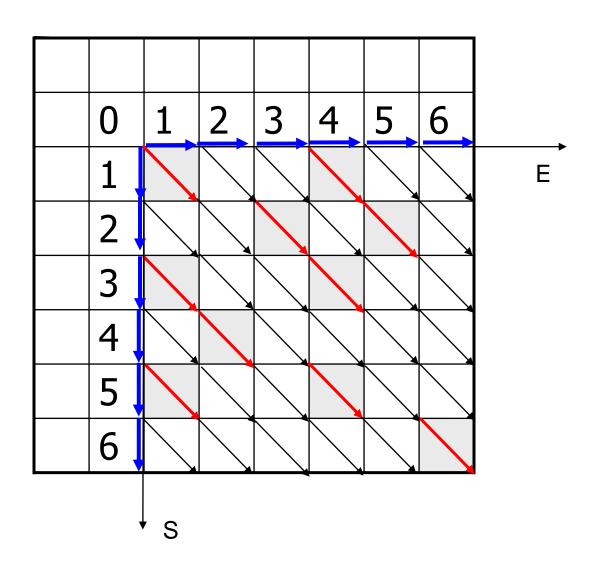
Fill values for i=1 (from left to right)



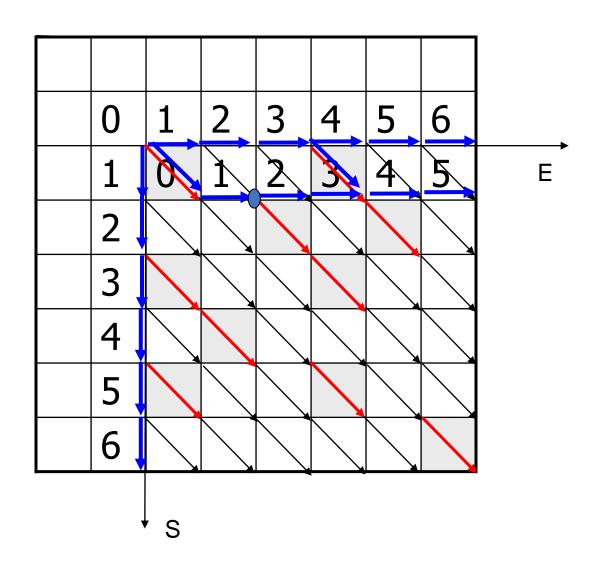
Fill the entire table (left-to-right top-down)



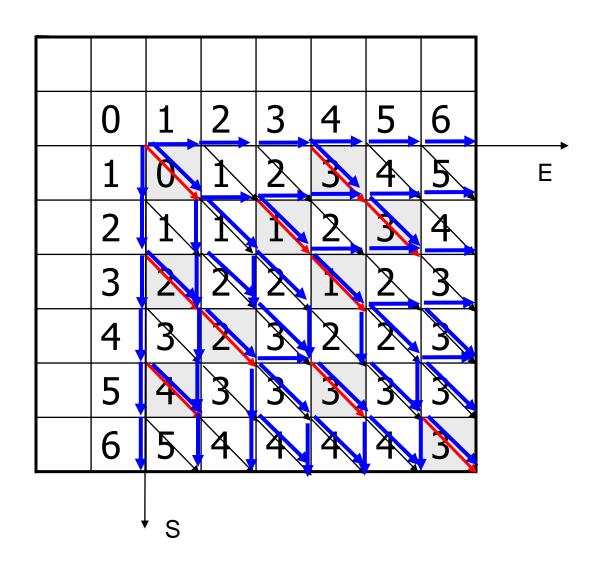
Keeping track of the source



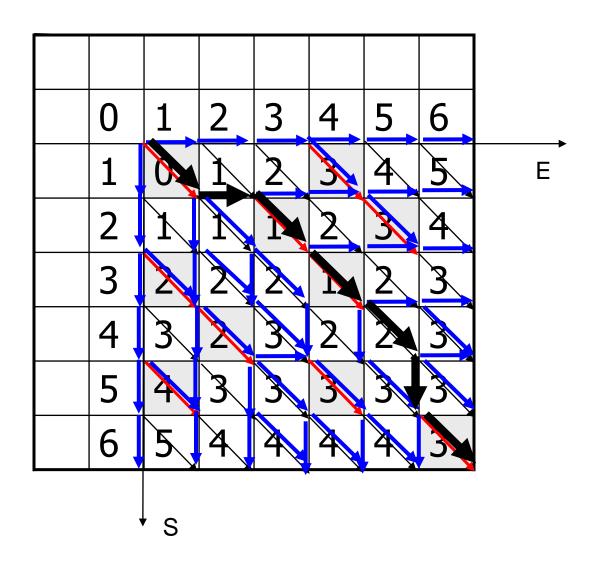
Keeping track of the source



Keeping track of the source



Trace back – how did we get the path with the cost 3?



Our first *Dynamic Programming* algorithm

Algorithm: cheapestPath (diagonalCost NxM)

```
allocate array DPTable (NxM)
DPTable [0][0]:=0
for i from 1 to N:
  DPTable [i][0]:=i
for j from 1 to M:
  DPTable [0][j]:=j
for i from 1 to N:
  for j from 1 to M:
    DPtable\ [i][j]:=min\ (DPtable\ [i-1][j-1]+diagonalCost\ [i][j],
                                    DPtable [i-1][j]+1, DPtable [i][j-1]+1)
return DPTable [N][M]
```

2 nested loops: O(N²)

Dynamic programming: when

- ☐ We want to optimize something: min, max
- ☐ The solution to the problem depends on the solutions to subproblems
- ☐ We would need the solutions to all subproblems
- Subproblems overlap

Dynamic programming: how

- ☐ The recurrence relation
- The bottom-up computation
- ☐ The traceback

"Programming" in "Dynamic programming" has nothing to do with programming!

- Richard Bellman developed this idea in 1950s working on an Air Force project
- At that time, his approach seemed completely impractical
- He wanted to hide that he is really doing pure math from the Secretary of Defense



Richard Bellman

... What name could I choose? I was interested in planning but planning is not a good word for various reasons. I decided therefore to use the word "programming" and I wanted to get across the idea that this was dynamic. It was something not even a Congressman could object to. So I used it as an umbrella for my activities.

Representative problems

- ☐ Edit distance
- ☐ Knapsack 01
- □ Shortest paths

Edit distance

Transforming one sequence into another: *edit operations*

- ☐ We can transform the first string S1 into the second S2 by applying a sequence of edit operations on S1 :
 - ☐ Deleting 1 symbol
 - ☐ Inserting 1 symbol
 - ☐ Replacing 1 symbol

S1	a	С	t			a	t	g
S2	а	Delete c	t	Insert a	Insert c	а	Delete t	g

In total, 4 edit operations

String alignment

An alignment of 2 strings is obtained by first inserting spaces (gaps), either into or at the end of both strings, and then placing 2 resulting strings one above the other, so that every character or space in either string is opposite a single character or space in the other string

Alignment

S1	а	С	t	_	-	а	t	g
S2	а	•	t	а	С	а	ı	g

4 gaps, no mismatches

Edit distance: definition

 The edit distance between two strings is defined as the minimum number of edit operations needed to transform one string into another

S1	a	С	t	a	t		g
C_{2}	_	Delete c		_	Replace t	Insert a	_
52	a		Ţ	a	C	а	g

In total, 3 edit operations

Optimal alignment

☐ An optimal alignment is obtained from the calculation of the edit distance

Optimal Alignment

S1	a	С	t	а	t		g
S2	a	Delete c	t	а	Replace t	Insert a	g

Edit distance=3

Is this really the smallest number of edit operations?

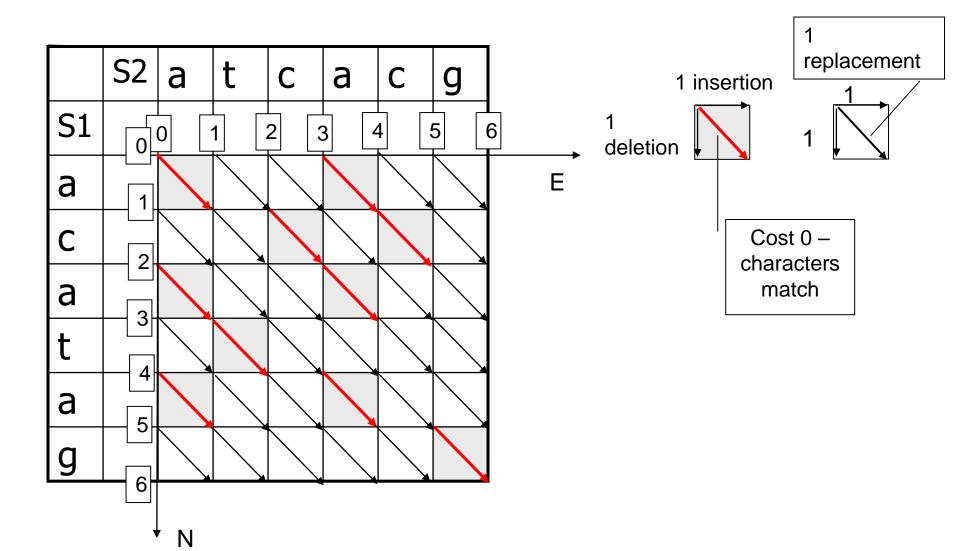
How do we compute edit distance in general?

The edit distance problem

Input: 2 strings S₁ and S₂

Output: the *edit distance* between two strings along with a sequence of the operations which describe the transformation

Full analogy with the cheapest path

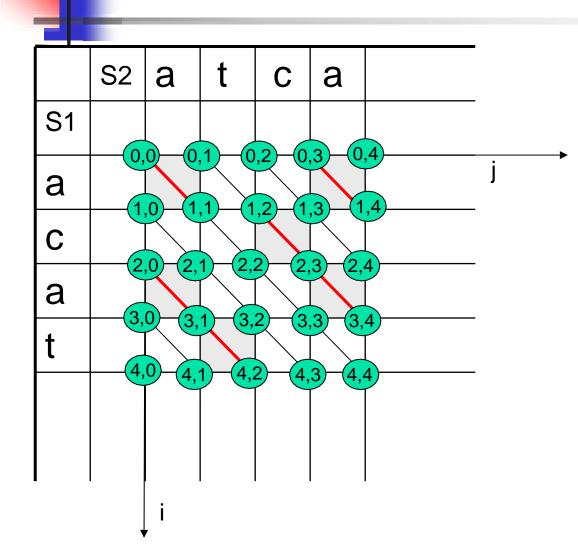


The dynamic programming solution to the edit distance problem

Trivially follows from the solution for the cheapest path:

- ◆ If we moved strictly down in the grid, we deleted (ignored) 1 symbol from S1
- ◆ If we moved strictly to the right, we inserted 1 symbol from S2 into S1
- ◆ If we moved by diagonal of cost 0, we matched the corresponding characters
- ◆ If we moved by diagonal of cost 1, we replaced one symbol in S1 with the corresponding symbol in S2

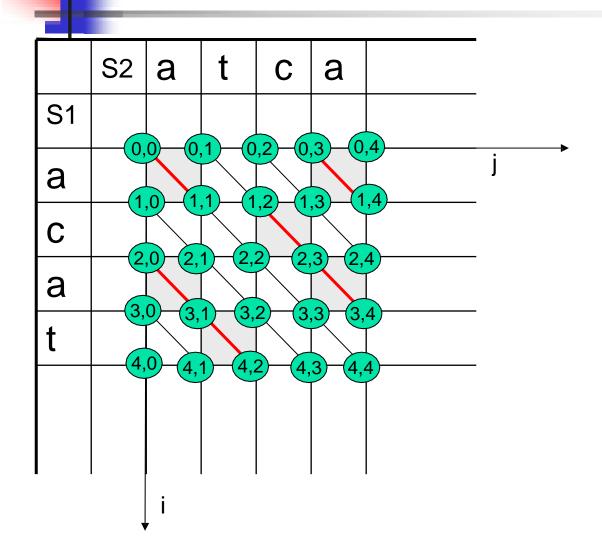
Useful abstraction: edit graph



An edit graph for a pair of strings S_1 and S_2 has $(N+1)^*(M+1)$ vertices, each labeled with a corresponding pair (i,j), $0 \le i \le N$, $0 \le j \le M$

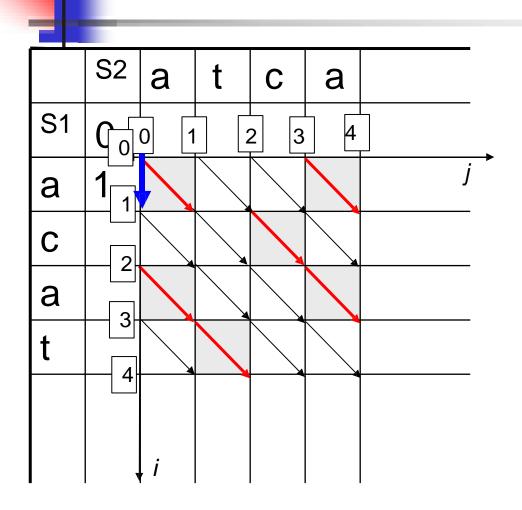
The edges are **directed** and their weight depends on the specific string problem: for the edit distance problem – red edges have cost 0, black edges have cost 1

The cheapest path in the edit graph



The cost of a cheapest path from vertex (0,0) to vertex (N,M) in this edit graph corresponds to the edit distance between S1 and S2, and the path itself represents a series of edit operations and an optimal alignment of S1 with S2

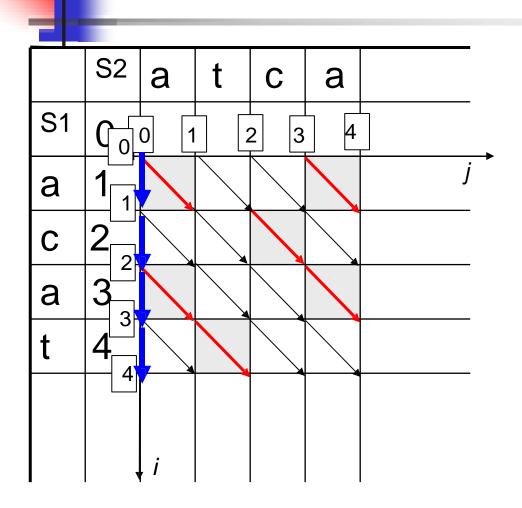
Calculating edit distance. Base condition



The minimum number of edit operations we need in order to transform string *a* into an empty string (of length 0) is 1 (deletion)

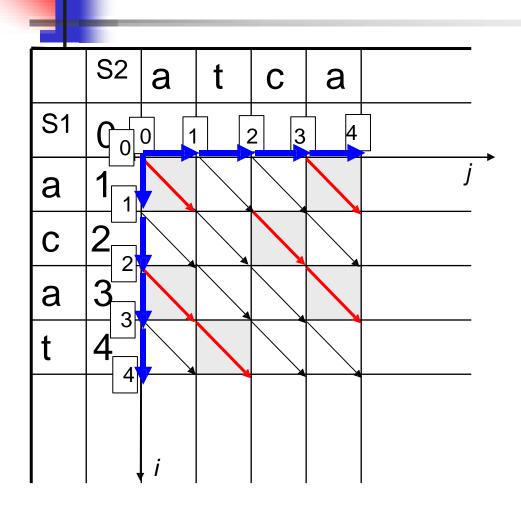
Therefore the minimum edit distance between ϵ and a is 1

Calculating edit distance. Base condition



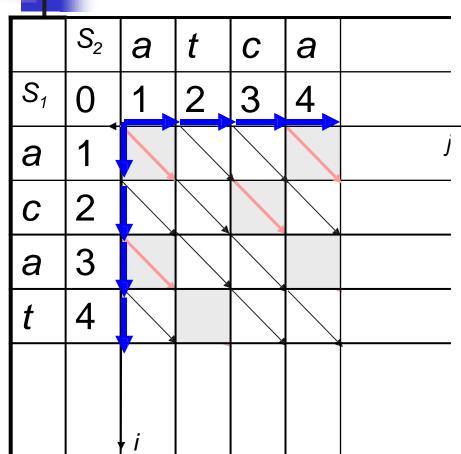
The same is true for ε and ac, aca, acat

Calculating edit distance. Base condition



In order to transform ε into a, we need to insert 1 character. This is the best way to do it, there is no cheaper way.

The same for transforming ε into *at*, *atc*, *atca* with 2, 3, 4 insertions respectively



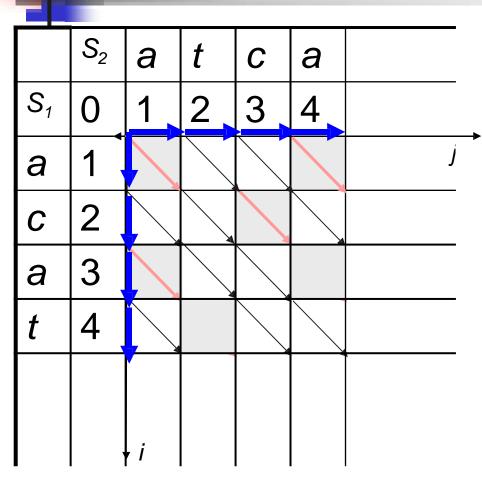
There are only 3 different ways to move through the next cell in the graph:

1. Increase both *i* and *j* (diagonal)

if S1[i] #S2[j]: 1 edit

if S1[i]=S2[j]: 0 edits

- 2. Increase only i (insert $S_1[i]$) with the cost 1
- 3. Increase only j (delete ignore $S_2[j]$) with the cost 1



Thus, if we know the edit distance

D[i-1,j-1], D[i-1,j] and D[i,j-1], we can correctly calculate D[i,j]

This is true since there are no other ways of moving through cell [i][j].

Reaching the top, left and top-left corners by different paths cannot produce a better value than is already in these 3 cells, since they contain the minimum cost by definition

	S_2	a	t	C	a	_
S ₁	0	1	2	3	4	
а	1,	O.	1	2	3	j
С	2					
а	3					
t	4					
						_
	,	, j				

$$D(i,j) = \min \begin{cases} D(i-1,j)+1 \\ D(i,j-1)+1 \\ D(i-1,j-1)+c(i,j) \end{cases}$$

where
$$c(i,j) = \begin{cases} 0 \text{ if } S1[i] = S2[j] \\ \\ 1 \text{ if } S1[i] \neq S2[j] \end{cases}$$

	S_2	a	t	C	a	
S ₁	0	1	2	3	4	
а	1,	Ò	1	2	3	j
С	2	1	1	1	2	
а	3					
t	4					
		, j				

$$D(i,j) = \min \begin{cases} D(i-1,j)+1 \\ D(i,j-1)+1 \\ D(i-1,j-1)+c(i,j) \end{cases}$$

where
$$c(i,j) = \begin{cases} 0 \text{ if } S1[i] = S2[j] \\ \\ 1 \text{ if } S1[i] \neq S2[j] \end{cases}$$

	S_2	а	t	С	a	
S_1	0	1	2	3	4	
а	1,	0	1	2	3	j
С	2	1	1	1	2	
а	3	2	2	2	1	
t	4					
		i				

$$D(i,j) = \min \begin{cases} D(i-1,j)+1 \\ D(i,j-1)+1 \\ D(i-1,j-1)+c(i,j) \end{cases}$$

where
$$c(i,j) = \begin{cases} 0 \text{ if } S1[i] = S2[j] \\ 1 \text{ if } S1[i] \neq S2[j] \end{cases}$$

	S ₂	а	t	C	a	
S_1	0	1	2	3	4	
а	1,	Ò	1	2	3	j
С	2	1	1	1	2	
а	3	2	2	2	1	
t	4	3	2	3	2	
	,	, j				

$$D(i,j) = \min \begin{cases} D(i-1,j)+1 \\ D(i,j-1)+1 \\ D(i-1,j-1)+c(i,j) \end{cases}$$

where
$$c(i,j) = \begin{cases} 0 \text{ if } S1[i] = S2[j] \\ \\ 1 \text{ if } S1[i] \neq S2[j] \end{cases}$$

The sequence of edit operations

	S_2	a	t	C	a	
S ₁	0	1	2	3	4	
а	1,	0	1	2	3	j
С	2	1	1	M	2	
а	3	2	2	2	1	
t	4	3	2	3	2	7
					•	
	,	, j				



Place a character in S1 opposite to a character in S2



Place a character in S1 opposite to a gap in S2



Place a character in S2 opposite to a gap in S1

<i>S1</i>	а	-	С	a	t
<i>S2</i>	а	t	С	a	-

Optimal alignment

<i>S1</i>	а	-	С	а	t
<i>S2</i>	а	t	С	а	-

Explanation:

 S_2 can be obtained from S_1 by a series of the following edit operations:

Insertion of *t* at position 2

Deletion of t at position 5

An optimal alignment is not unique

<i>S1</i>	-	а	t	t	а	а	g
<i>S2</i>	t	а	-	t	С	а	g
<i>S1</i>	_	а	t	t	а	а	g
<i>52</i>	t	а	t	С	а	_	g

2 different alignments with the optimal edit distance 3